

# Support Vector Machines

Mon Feb 22

$$y = \text{sign}(w^T x + w_0)$$

$$P(y=+1) = \frac{1}{1 + \exp(-w^T x)}$$

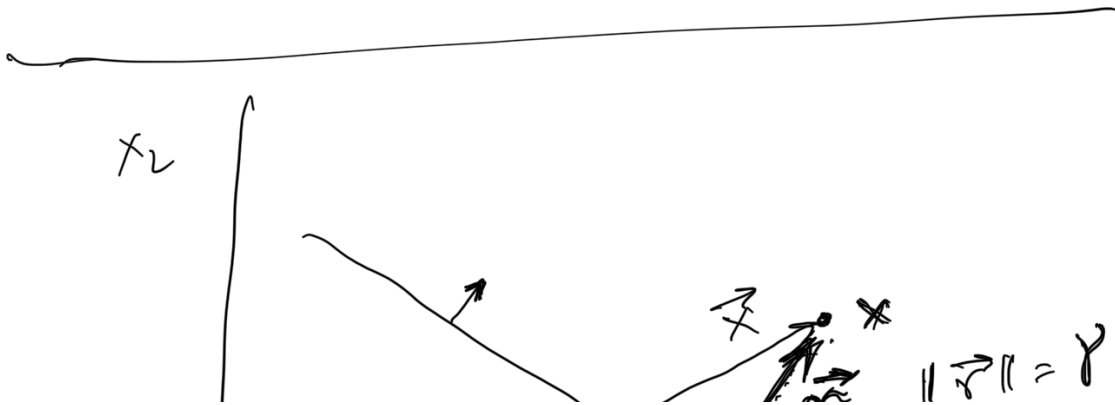
If  $P(y=+1) \geq 0.5$   $\hat{y} = +1$

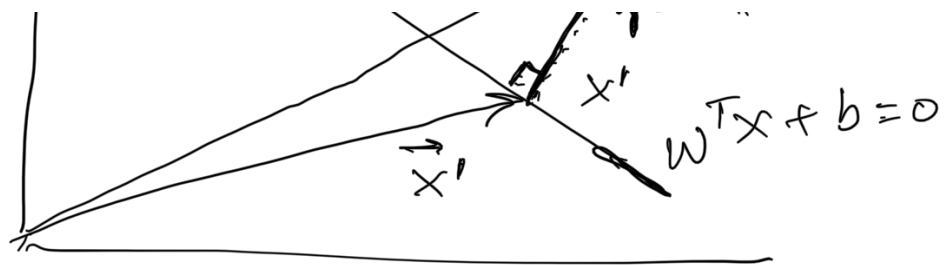
For a new data point:

$$P(y=+1) = 0.95$$

For another data point:

$$P(y_i=+1) = 0.55$$





$$\vec{x} = \vec{x}' + \vec{\gamma}$$

$$\vec{x}' = \vec{x} - \vec{\gamma}$$

$x_1$

$$\hat{w} = \frac{\vec{w}}{\|\vec{w}\|} \rightarrow \text{unit vector orthogonal to the line}$$

$$\|\vec{w}\| = \sqrt{w_1^2 + w_2^2 + \dots}$$

$$\vec{\gamma} = \gamma \hat{w} = \frac{\gamma \vec{w}}{\|\vec{w}\|} = \frac{\gamma \vec{w}^T \vec{w}}{\|\vec{w}\|}$$

$$\vec{x}' = \vec{x} - \frac{\gamma \vec{w}}{\|\vec{w}\|}$$

Since  $\vec{x}'$  lies on the decision line  
 $w^T \vec{x}' + b = 0$

$$w^T \left( \vec{x} - \frac{\gamma \vec{w}}{\|\vec{w}\|} \right) + b = 0$$

$$w^T \vec{x} - \gamma \frac{w^T w}{\|\vec{w}\|} + b = 0$$

$$y \cdot w^T w = w^T x + b$$

$$\|w\|$$

$$y = \frac{w^T x + b}{\|w\|}$$

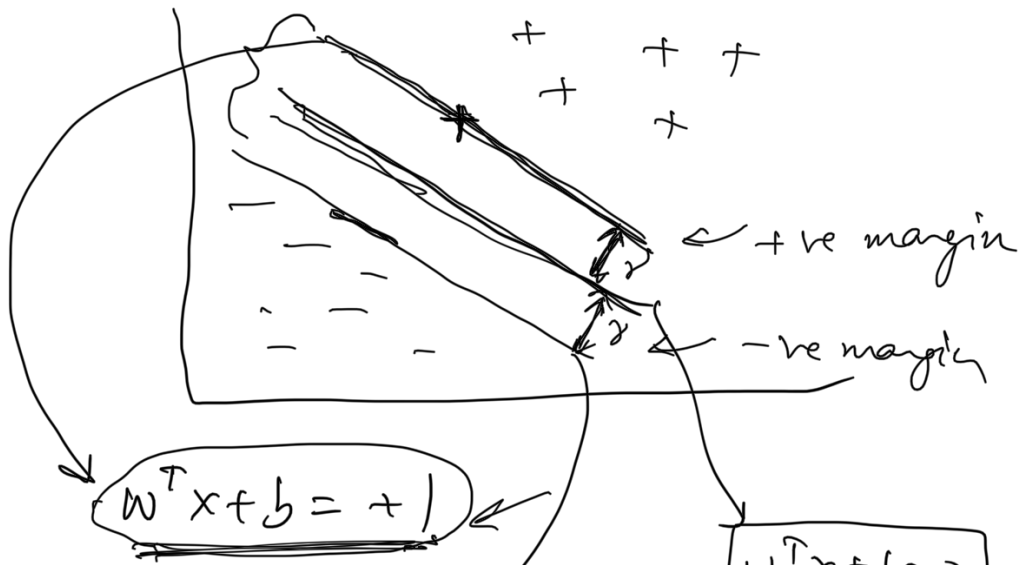
Since  $w^T w = \|w\|^2$

for a -ve example

$$y = - \frac{(w^T x + b)}{\|w\|}$$

$$y = \left( y \frac{w^T x + b}{\|w\|} \right)$$

This is margin of an example.



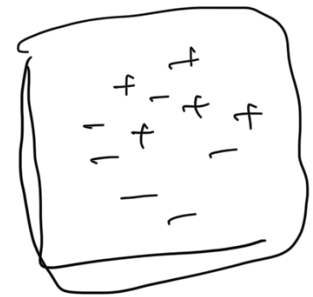
$$\underline{w^T x + b = -1}$$

$$\underline{w^T x + b = 0}$$

Distance between two margins:

will be

$$\frac{2}{\|w\|}$$



$i^{\text{th}}$  training example:  $\underline{x_i}, \underline{y_i}$

If  $w, b$  has to correctly classify this instance

$$\underline{y_i (w^T x_i + b) \geq 0}$$

If  $w, b$  have to be on the correct side of the margin:

$$\underline{y_i (w^T x_i + b) \geq 1}$$

Opt with equality constraints.

$$f(x, y) = x^2 + 2y^2 - 2$$

$$h(x, y) = \boxed{x + y - 1 = 0}$$

$$L(x, y, \beta) = x^2 + 2y^2 - 2 + \beta(x + y - 1) = 0$$

$$\frac{\partial L}{\partial x} = 2x + \beta = 0$$

$$\frac{\partial L}{\partial y} = 4y + \beta = 0$$

$$\frac{\partial L}{\partial \beta} = \underline{x + y - 1 = 0}$$

$$\begin{aligned} 4y - 2x &= 0 \\ x &= 2y \end{aligned}$$

$$x = 1 - y$$

$$1 - y = 2y$$

$$\boxed{y = \frac{1}{3} \quad x = \frac{2}{3}}$$

Wednesday Feb 24

$$\nabla f(w_1, w_2) = \lambda \nabla g(w_1, w_2)$$

$$g(w_1, w_2) = 0$$

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$$L = f(w_1, w_2) + \lambda g(w_1, w_2)$$

$$\nabla_{(w_1, w_2)} L = \nabla f(w_1, w_2) + \lambda \nabla g(w_1, w_2) = 0$$

$$\nabla_{(w_1, w_2)} g(w_1, w_2) = 0$$

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$$f(x, y) = x^3 + y^2$$

$$g(x): x^2 - 1 \leq 0$$

$$L(x, y, \alpha) = f(x, y) + \alpha g(x, y)$$

$$= x^3 + y^2 + \alpha(x^2 - 1)$$

$$w = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix}$$

$$\min_{w_1, w_2} \frac{w_1^2 + w_2^2}{2}$$

$$\|w\|^2 = w_1^2 + w_2^2$$

$$\begin{aligned} \text{s.t. } & 1 - (-1)(w_1 + w_2 + b) \leq 0 \quad y_1 = -1 \\ & \equiv 1 + w_1 + w_2 + b \leq 0 \quad x_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \\ & 1 - (+1)(2w_1 + 2w_2 + b) \leq 0 \quad y_2 = +1 \\ & \equiv 1 - 2w_1 - 2w_2 - b \leq 0 \quad x_2 = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \end{aligned}$$

$$L = \frac{w_1^2 + w_2^2}{2} + \alpha_1 (1 + w_1 + w_2 + b) + \alpha_2 (1 - 2w_1 - 2w_2 - b)$$

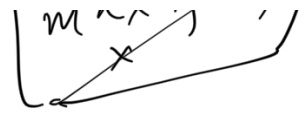
$$\alpha_1, \alpha_2 \geq 0$$

$$\frac{\partial L}{\partial w_1}, \quad \frac{\partial L}{\partial w_2}, \quad \frac{\partial L}{\partial \alpha_1}, \quad \frac{\partial L}{\partial \alpha_2}, \quad \frac{\partial L}{\partial b}$$

$$L(w, \alpha, \beta)$$

$$\dots \text{ and } f(x)$$

Assume  $w$  is fixed



$$\Theta_P(w) \quad \max_{\alpha, \beta | \alpha_i \geq 0} L(w, \alpha, \beta)$$

$$\min_w \Theta_P(w)$$

min-max is going to give us the optimal solution

what if we solve:

$$\max_{\alpha, \beta | \alpha_i \geq 0} \left[ \min_w L(w, \alpha, \beta) \right] \rightarrow \underline{\underline{\text{dual}}}$$

max-min

$$\text{max-min} \leq \text{min-max}$$

"duality-gap"

$$f(w_1, w_2)$$



$$L_p = \frac{\|w\|^2}{2} + \sum_{i=1}^N \alpha_i \{1 - y_i (w^T x_i + b)\}^2$$

$$\frac{\partial L}{\partial w} = \frac{1}{2} \cdot 2w + \sum_{i=1}^N \alpha_i (-y_i x_i)$$

$$= w - \sum_{i=1}^N \alpha_i y_i x_i$$

$$\|w\|^2 = w^T w$$

$$\frac{d}{dw} w^T w = 2w$$

$$w = \sum_{i=1}^N \alpha_i y_i x_i$$

$$\sum_{i=1}^N \alpha_i y_i = 0$$

$$L_p = \frac{\|w\|^2}{2} + \sum_{i=1}^N \alpha_i \{1 - y_i (w^T x_i + b)\}^2$$

$$= \frac{1}{2} w^T w + \sum_{i=1}^N \alpha_i \{1 - y_i (w^T x_i + b)\}^2$$

Replace  $w$  with  $\sum_{i=1}^N \alpha_i y_i x_i$

Solve the dual to get  $\alpha_1, \alpha_2, \dots, \alpha_N$

↙  
crossprod

Feed the  $\alpha$ 's to get  $w$

Friday Feb 26

$(w^T x + b)$

$$J(w) \underset{w, b}{\text{min.}} \frac{\|w\|^2}{2}$$

$$\text{s.t. } 1 - [y_i (w^T x_i + b)] \leq 0 \quad i=1, \dots, N$$

$$L_p(w, b, \alpha) = \frac{\|w\|^2}{2} + \sum_{i=1}^N \alpha_i \{1 - y_i (w^T x_i + b)\}$$

$$\text{s.t. } \boxed{\alpha_i \geq 0} \quad i=1, \dots, N$$

↖  
Primal

$$L_D(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{m,n=1}^N \alpha_m \alpha_n y_m y_n (x_m^T x_n)$$

$$\sum_{i=1}^N \alpha_i y_i = 0, \alpha_i \geq 0, i=1, \dots, N$$

Dual  $\nearrow$

$$W = \sum_{i=1}^N \alpha_i y_i x_i$$

$$\begin{bmatrix} x_1 & , & y_1 \\ x_2 & , & y_2 \end{bmatrix} \quad N=2$$

$$L_D(\alpha) = (\alpha_1 + \alpha_2) - \frac{1}{2} \left[ \alpha_1 \alpha_1 y_1 y_1 x_1^T x_1 \right. \\ \left. + \alpha_1 \alpha_2 y_1 y_2 x_1^T x_2 \right. \\ \left. + \alpha_2 \alpha_1 y_2 y_1 x_2^T x_1 \right. \\ \left. + \alpha_2 \alpha_2 y_2 y_2 x_2^T x_2 \right]$$

$$\text{s.t. } \alpha_1 y_1 + \alpha_2 y_2 = 0$$

$$\text{and } \alpha_1 \geq 0$$

$$\text{and } \alpha_2 \geq 0$$

Find  $\alpha_1$  and  $\alpha_2$  that maximize  $L_D(\alpha)$

$$W = \alpha_1^* y_1 x_1 + \alpha_2^* y_2 x_2$$

$$b = \frac{w^T x_1 + w^T x_2}{2}$$

for a test instance  $x^*$   $y^* = ?$

$$y^* = \text{sign}(w^T x^* + b)$$

$$= \text{sign}\left(\left(\sum \alpha_i y_i x_i\right)^T x^* + b\right)$$

$$= \text{sign}\left(\sum_{i=1}^N \alpha_i y_i \underline{x_i^T x^*} + b\right)$$

$$\begin{array}{l} J(w, b) \\ \rightarrow L_p(w, b, \alpha) \\ \rightarrow \underline{L_D(\alpha)} \end{array}$$

$$\text{KKT \#5} \quad \alpha_i (1 - y_i \{w^T x_i + b\}) = 0 \quad \forall i$$

For any  $x_i$  that lies on one of the

margins:

$$y_i \{ w^T x_i + b \} = 1$$

and for any  $x_i$  that does not lie on the margin:

$$y_i \{ w^T x_i + b \} > 1$$

→  $\alpha_i$  will be 0

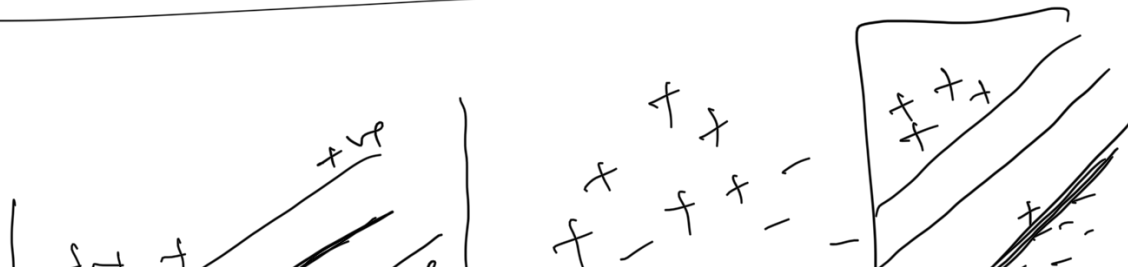
Support vectors:

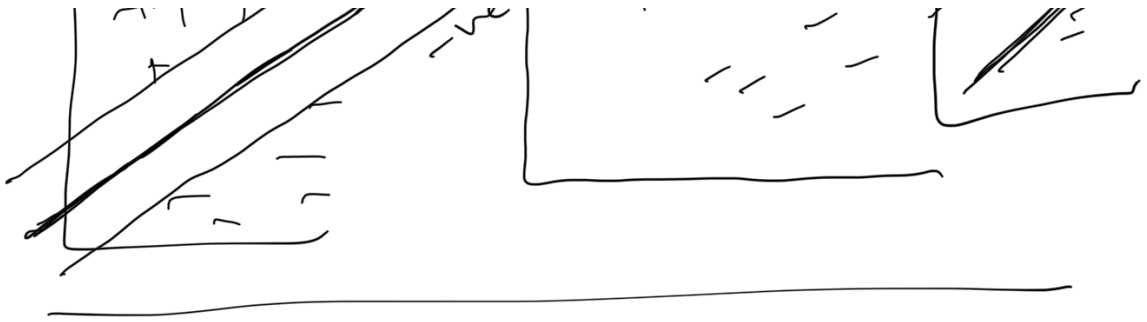
$$y^* = \text{sign}(w^T x^* + b)$$

$$= \text{sign}\left( \left( \sum \alpha_i y_i x_i \right)^T x^* + b \right)$$

$$= \text{sign}\left( \sum_{i=1}^N \alpha_i y_i (x_i^T x^*) + b \right)$$

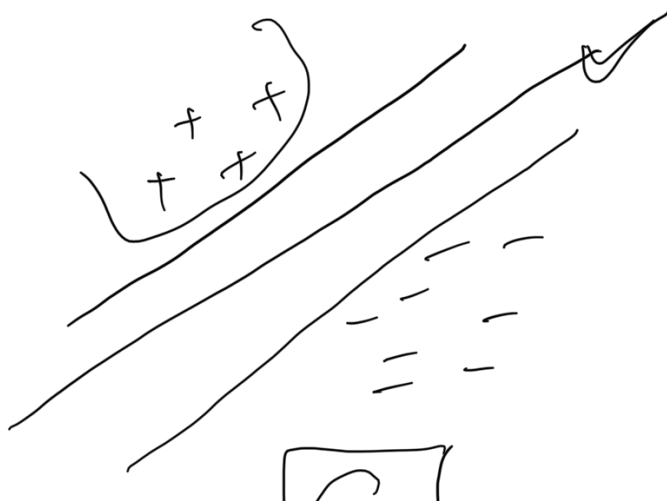
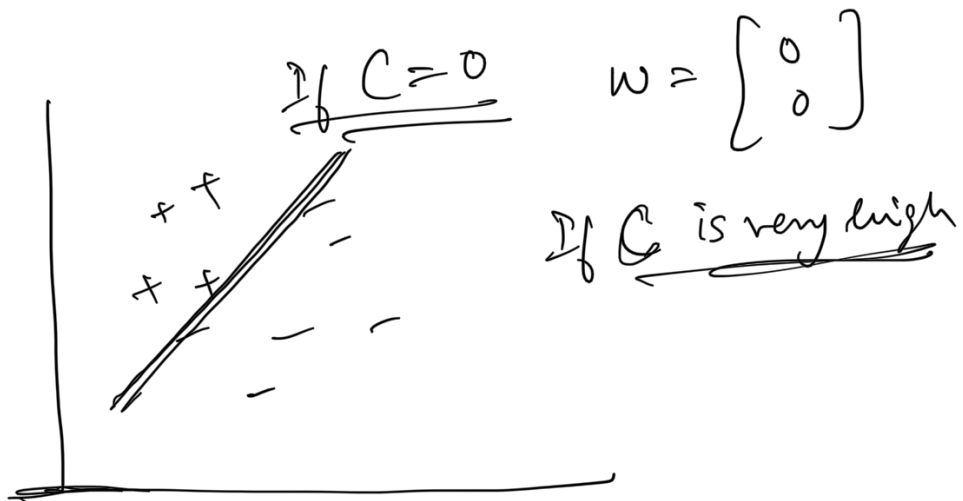
$$y^* = \text{sign}\left( \sum_{i \in S} \alpha_i y_i (x_i^T x^*) + b \right)$$





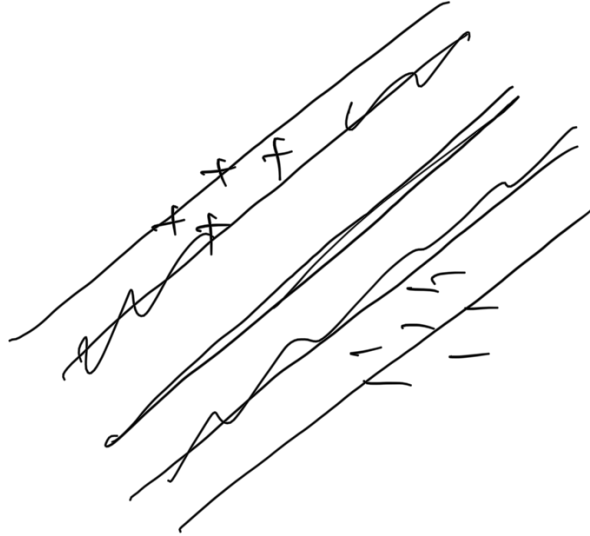
$\xi_i \rightarrow$  slack for training example  $i$

$$|1 - y_i (w^T x_i + b)|$$

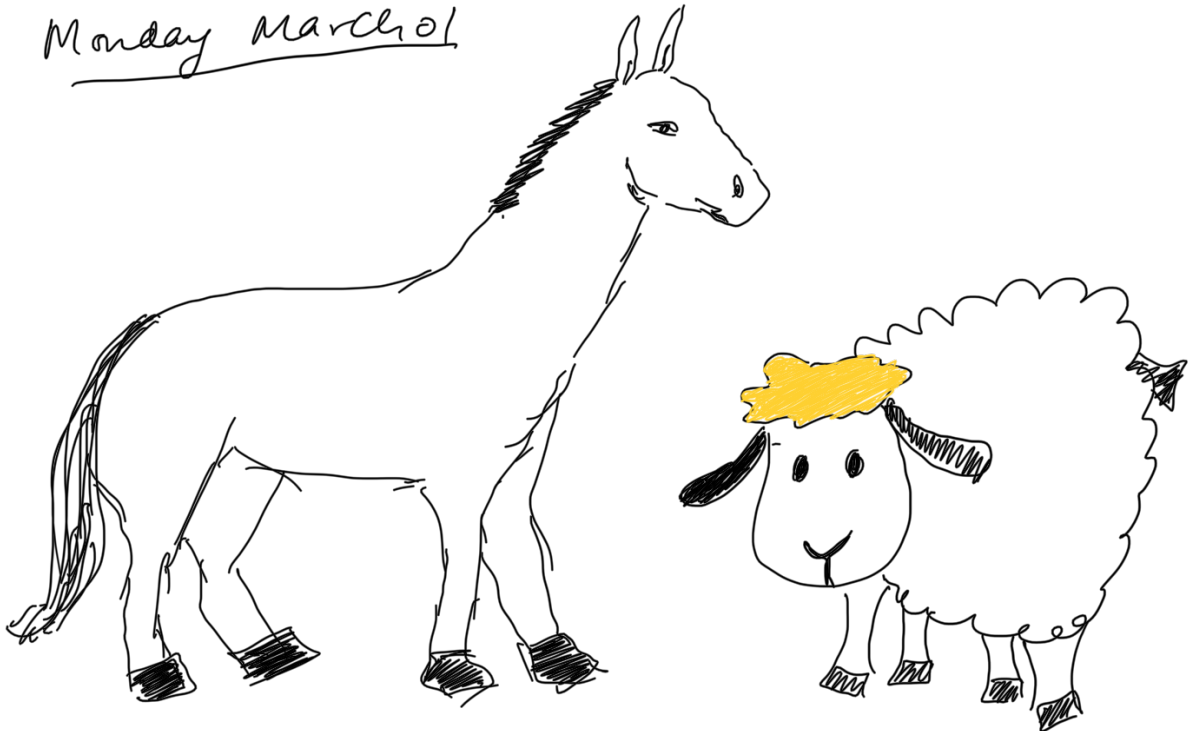




# (Bias-Variance Tradeoff)



Monday March 01



$$\min L(w, b) = \|w\|^2 + C \sum_{i=1}^N \epsilon_i$$

$w, b$

$i=1$

$$\text{s.t. } y_i(w^T x_i + b) \geq 1 - \xi_i$$

$$\xi_i \geq 0$$

$i=1, \dots, N$

Small  $C$   
~~High bias~~  
mule

large  $C$   
high variance  
~~sheep~~

bias-variance tradeoff